# A Proposed technique for Brain MRI Using Region **Based Segmentation**

Harman Kataria, Alka Jindal

Abstract-The paper presents an efficient brain MRI region based segmentation technique that accurately classifies the abnormal tissue from normal tissue. All methods are used for noisy and blurred images and perform segmentation in improved way. A comparison of three different brain MRI segmentation methods, viz., improved level segmentation method, local region based active contour and variational level set formulation method along with their comparison and their results. These methods are applied on both 2d as well as 3d images.

Keywords-Active Contour, Segmentation, Intensity Inhomogenity, Magnetic Resonance Image (MRI), Level Set Method, Local Region based Active contour.

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# **1 INTRODUCTION**

Medical imaging plays an important role in patient diagnosis. To examine the disease of patient imaging technology is used. MRI and PET/CT is vital diagnostic imaging techniques. MRI and PET/CT provides a good contrast between the different soft tissues of the brain. Combined PET/CT instrumentation is a new type of advanced medical imaging equipments which is a highperformance combination of PET and CT scanners [1].

Segmentation is a challenging task. Segmentation helps in diagnosis of various diseases. We can apply research on the segmented data such as classifying a voxels, volumetric analysis of particular tissues and structures.

We can categorize the active contour model into two parts edge based models [2] and region based models [3]. This paper presents the segmentation methods Improved Level Set[4], Local Region based active contour[5] and variational level set method[6] and proposed model for extracting the abnormal tissue from the brain MRI images.

This paper presents the method that applies on both homogenous and non homogenous method. Intensity homogeneity occurs due to technical limitations or an artifact introduced by the object and it is mainly present in real images. The radio frequency coils produces nonuniform magnetic field that arise inhomogenity in magnetic resonance image (MRI). We require segmentation method to correct the intensity inhomogenity as a preprocessing step [7].

The paper is organized as follows. In section II we present different image segmentation methods. Section III describes the experimental results and discussion Section IV describe the comparison of all segmentation method Section V conclude the paper

### 2 SEGMENTATION METHODS

Segmentation of brain is very important for doctors to make a definite diagnosis. The segmentation methods for Brain MRI are:

#### 2.1 Improved level Set Method

The author Jia Di et al[4], proposed a C-V model that makes segmentation better than the other model. Active contour model is used to evolve the curve on the given image in order to detect objects in the image. C-V model divides the entire region into two parts one is inside part and the other is outside part and we can get the edges from the end of curves iteration. The energy function is following as

$$\begin{split} E(c_1, c_2, C) &= \mu \int_c^{\cdot} ds + \lambda_1 \iint_{\Omega_1} (I - c_1)^2 dx dy + \lambda_2 \iint_{\Omega_2} (I - c_2)^2 dx dy \\ c_2 dx dy \end{split}$$
(1)

There are two energy functions internal and external energy and each iteration should compute internal average gray c1 and external gray c2, and for solution we use Heaviside function

$$F_1(c) = \lambda_1 \iint_{\Omega} (I - c_1 2 H u dx dy)$$
(2)

$$F_{2}(c) = \lambda_{2} \iint_{\Omega} (l - c_{2})^{2} [1 - H(u)] dx dy$$
(3)

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$$c_1^n = \frac{\sum_{i,j} H_{\epsilon}(u_{ij}^n) I_{ij}}{\sum_{i,j} H_{\epsilon}(\mu_{ij}^n)} \qquad \qquad c_2^n = \frac{\sum_{i,j} (1 - H_{\epsilon}(\mu_{ij}^n) I_{ij})}{\sum_{i,j} (1 - H_{\epsilon}(\mu_{ij}^n))}$$
(4)

#### 2.2Local Region Based Active Contour

Local Region Based Active Contour is a region based method that is insensitive to noise and it is robust against the initial curve placement. It segments non-homogenous objects. It uses smaller local regions to segment the object rather than the global region [5]. Three types of energies can be used with this methods uniform modelling energy, mean separation energy and histogram separation energy [8]. The final energy is shown as below:

$$E(\phi) = \int_{\Omega_{x}}^{\cdot} \delta\phi(x) \int_{\Omega_{y}}^{\cdot} A(x, y) \cdot F(u_{o}(y, \phi(y))) dy dx$$

$$+ \qquad \lambda_{1} \int_{\Omega_{x}}^{\cdot} \delta\phi(x) ||\nabla\phi(x)|| dx$$
(5)
$$A(x, y) = \begin{cases} 1, ||x - y|| < r \\ 0, & otherwise \end{cases}$$
(6)
$$C_{1} = \frac{\int_{\Omega_{y}}^{\cdot} H^{\Phi(y)} u_{o} dy}{\int_{\Omega_{y}}^{\cdot} (1 - H^{\Phi(y)}) dy}$$
(7)
$$C_{2} = \frac{\int_{\Omega_{y}}^{\cdot} (1 - H^{\Phi(y)}) u_{o} dy}{\int_{\Omega_{y}}^{\cdot} (1 - H^{\Phi(y)}) dy}$$
(8)

Where  $C_1$  and  $C_2$  are the mean intensities of the interior and exterior regions.  $\delta$  is dirac function, *F* is Force function,  $u_o$  is input image.

#### 2.3 Variational Level Set Formulation

The author Chunming Li et.al[6] proposed a Variational level set formulation method that is a region based method. This algorithm segments the whole image. It overcomes the problem that occurred due to intensity inhomogeneity. In this method we first define Region Scalable fitting (RSF) energy function and localization is performed by two fitting function f1, f2 and  $K_{\sigma}$ . This algorithm is able to segment inhomogeneous objects. The standard gradient descent method is use to minimize the energy functional. The minimization equation is.

$$E(\phi) = \lambda_1 \int_{\Omega} \int_{\Omega} K_{\sigma}(x-y) |I(y) - f_1(x)|^2 H(\Phi(x)) dy dy$$
  
+ $\lambda_2 \int_{\Omega} \int_{\Omega} K_{\sigma}(x-y) {}^2 H(\Phi(x)) dy dx$   
+ $v \int_{\Omega} \delta(\phi(x)) ||\nabla \phi(x)|| dx + \mu \int_{\Omega} \frac{1}{2} (||\nabla \phi(x)|| - 1)^2 dx$   
(9)

Where I(x) is the image intensity at pixel x, H is a Heaviside function,  $K_{\sigma}$  is a Gaussian kernel defined as:

$$K_{\sigma}(u) = \frac{1}{(2\Pi)^{n/2} \sigma^n} e^{-\|u\|^2/2\sigma^2}$$
(10)

With a scale parameter  $\sigma$ >0, f1 and f2 are two functions centred at pixel as

$$f_{1}(x) = \frac{K_{\sigma}*(H\phi(x)I(x)}{K_{\sigma}*H(\phi(x))}$$
(11)
$$f_{2}(x) = \frac{K_{\sigma}*((1-H(\phi(x))))}{K_{\sigma}*(1-H(\phi(x)))}$$
(12)

 $\lambda_1$  and  $\lambda_2$  are two constants that have been set 5 in the interface. The evolution equation is defined as below.

$$\begin{split} \frac{\delta \varphi}{\delta t} &= \delta(\phi(x)\lambda_1(\int_{\Omega} K_{\sigma}(x-y)|I(y) - f_1(x)|^2 dy + \lambda_2 \int_{\Omega} K_{\sigma}(x-y)|y-f(x)|^2 dy + \delta(\phi x k + \mu (\nabla 2\phi(x-k))) \end{split}$$
(13)

 $\phi$  is a signed distance function.

The first two terms is a data fitting term [9], these terms are used for driving active contour toward object boundaries. The third and fourth terms are used for smoothening and maintain the regularity of the contour.

#### 2.4 Proposed Model

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Harman Kataria is currently pursuing masters degree program in Computer science engineering in PEC University of Technology, INDIA, E-mail: <u>hrmn.kataria@gmail.com</u>

Alka Jindal is assistant professor with Information Department in PEC University of Technology, INDIA E-mail:alka\_er@rediffmail.com

The proposed model, is a variation of variational set level, peculiarly. We can extract the tumour itself without the background of the image. This can be done with inclusion of properties like solidity and eccentricity. The proposed model can also be applied on nonhomogenous images. The model takes into account in reduction of iterations and hence increases in the speed.

# **3 EXPERIMENTAL RESULTS AND** DISSCUSSION

In order to test the performance and discuss the comparison between the Improved Level Set Method [4], Local Region Based Active Contour [5] and Variational Level Set Formulation [6] and the proposed model. In this paper these algorithm has been tested with synthetic images of T2 Weighted brain MRI. The discussed algorithms were implemented in MATLAB. We use the various parameters for comparisons viz., the no of iterations, intensity homogeneity and time taken by the algorithm to segment the brain MRI image. All these methods applied on a noisy synthetic image. The phenomenon of pre-processing and post processing is avoided so that we can compare the results precisely.

All these methods accurately segment the tissues and all methods are independent of the location of the initial contour. The first method is based on images with homogenous foreground and background. The second and third method is based on both non-homogenous foreground and background images.

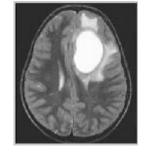
# **4 COMPARISONS**

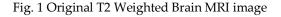
A Comparison of these algorithms is discussed in the above table. The improved level set method [4] should be applied to homogenous foreground and background images in Fig.2(c) it does not segment the tumour portion. Local Region Based active contour [5] accurately segment the image shown in Fig.3(c) but the problem is to initialize the contour for each and every image. Variational Level Set formulation [6] segment the whole image and this method can accurately show the tumour part in Fig.4(c). Number of iteration of these algorithms is given in table 1. The proposed model used the properties like scalability and

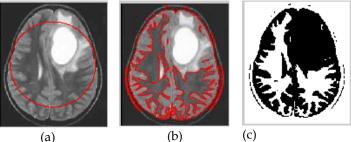
eccentricity to reduce the no of iterations and increase the speed of the model. The proposed model applied on both homogenous and nonhomogenous brain MRI images.

Table 1 Comparison of Segmentation Techniques

Parameters		Segmentation Alg
	Improved Level Set Method[4]	Localized regior Active contour[5]
Nature	Region based	Region based
Iterations	200	430
Noise sensitivity	No	No
Time Performance	It takes more time than other two methods.	It takes more the less than the first
Intensity Homogeneity	Homogenous foreground and background	Both homogeno non homogenous
Solidity & Eccentricity	These properties were not used in this model	These properties used in this mode







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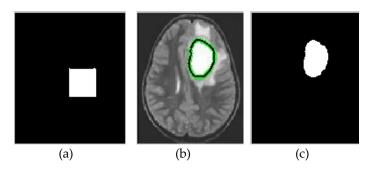


Fig.3 Results of the Local Region Based Method (a) Initialization (b)Final Contour 430 iterations (c) Final segmentation.

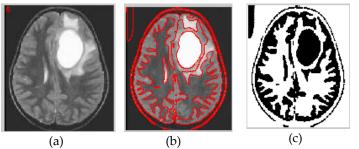


Fig.3 Results of the Variational Level Set Formulation (a) Initialization (b) Final Contour 150 iterations (c) Final segmentation.

# **5 CONCLUSION**

In this paper, various region based segmentation algorithm for brain MRI such as Improved Level Set, Local Region based active contour and Variational Level Set formulation has been discussed. Amongst all the segmentation method discussed Variatonal Level Set Formulation is the best segmentation method in terms of the classification of the tissue recognition and tumour extraction. It clearly segments the whole image and can be applied to both homogenous and non homogenous images. In this method there is no need to initialize the contour. In localized Level Set method the problem is to initialize the contour. Improved Level Set method should be applied to only homogenous images.

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